

dav1d is an AV1 (video) decoder



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#VDD2018, sponsored by Google



dav1d project is sponsored by the AOM Alliance

dav1d: introduction

- AV1 is the new video codec by the Alliance for Open Media (AOM)
 - 20-30% lower bandwidth for the same quality content
 - Intended users are internet video streaming services (Netflix, Youtube, etc.)
 - There is currently only one decoder: libaom we want to fix that
- Goals of our project:
 - Smaller binary size
 - Smaller memory footprint (vs. libaom)
 - Lower CPU usage
 - Multi-threaded
 - Cross-Platform
 - Maintainable & Easy to understand
 - Well-integrated in downstream tools / applications
 - Libre & actually Open Source

dav1d: the fine prints

BSD license

- Unusual for us
- Same as libvorbis, opus *RMS approved*
- We want forks (notably for hardware people)
- We want everyone to ship it (including OS and browsers)
- Outside of FFmpeg, yet easy to integrate (Simple API)

VideoLAN project

Technical details

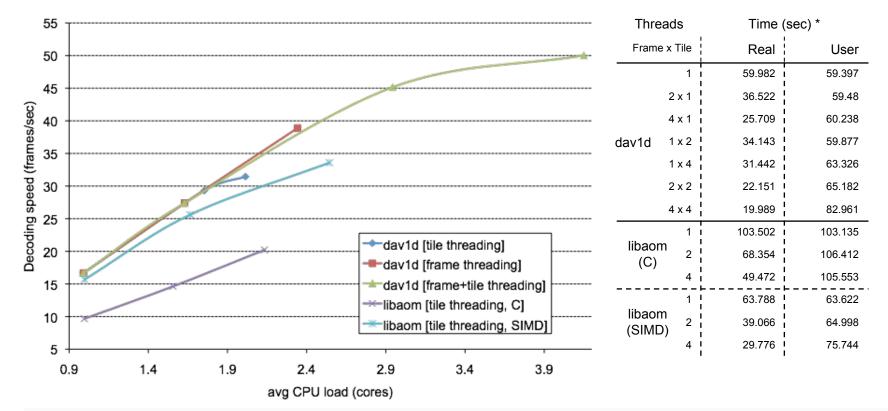
- C99
 - \circ $\,$ No VLA, No Complex $\,$
 - No GNU extension
- ASM
 - No intrinsics
 - ASM files, like in x264 and FFmpeg
- Buildsystem
 - Meson, ninja
 - MSVC, Xcode...
- Tools
 - C or Rust
 - MFC in C++

Footprint (= size) *

	dav1d	libaom		
Source (kLOC)	28.5	262.8	0>	Smaller source code
Binary (MB)	0.64	1.73	∘►	Smaller binary executable
Memory (MB) **	42.8	162.9	o>	Smaller runtime memory footprint

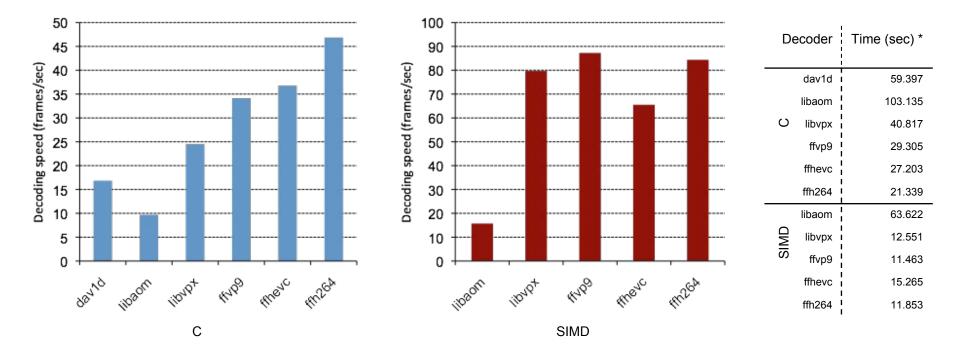
* av1/encoder in libaom excluded, SIMD excluded (*.[ch] only), built using -DCONFIG_AV1_ENCODER=0 -DAOM_TARGET_CPU=generic ** when playing http://download.opencontent.netflix.com.s3.amazonaws.com/AV1/Chimera/Chimera-AV1-8bit-1920x1080-6736kbps.ivf

CPU usage (= speed)



* when playing 1000 frames of http://download.opencontent.netflix.com.s3.amazonaws.com/AV1/Chimera/Chimera-AV1-8bit-1920x1080-6736kbps.ivf

Speed compared to other video codecs



* when playing 1000 frames (single-threaded) of Chimera-AV1-8bit-1920x1080 compressed using ffmpeg -c:v lib{x264/x265/vpx-vp9} @ 4mbps

High-level overview of decoding process (1)

```
main()

davld_init();
DavldContext *c;
davld_open(&c, ..);
for (;;) {
    // read data (e.g. from file)
    DavldData *in = ..;
    DavldPicture pic = { 0 };
    davld_decode(c, data, &pic);
    // do something with output pic
    ..
    davld_picture_unref(&pic);
}
davld_close(c);
```

```
dav1d_decode() → parse_obus()
```

```
for (;;) {
    obu type = ...;
    switch (obu type) {
    case OBU SEQ HDR:
        parse seq hdr(..);
        Break;
    case OBU FRAME:
    case OBU FRAME HDR:
        parse frame hdr(..);
        if (obu type == OBU FRAME HDR)
            break;
    case OBU TILE GRP:
        parse tile hdr(..);
        break;
    if (full frame available)
        submit frame(..);
```

High-level overview of decoding process (2)

(main thread)

(frame thread)

(tile thread)

```
submit frame() -> decode frame() -> decode tile sbrow()
                                                         for (int sbx = hdr->sb col[col];
  setup tile data structures
                                                              sbx < hdr->sb col[col + 1]; sbx++)
for (int row = 0; row < hdr->tile rows; row++)
   for (int col = 0; col < hdr->tile cols; col++)
        tile data[tile idx++] = ...
                                                             decode sb(..., seqhdr->sb128 ? BL 128X128 : BL 64X64);
// decode tiles (block parsing & reconstruction)
for (int pass = use 2pass; pass <= 2 * use 2pass;</pre>
    pass++)
{
    for (int row = 0; row < hdr->tile rows; row++) {
        for (int sby = hdr->sb row[row];
             sby < hdr->sb row[row + 1]; sby++)
                                                                              decode sb()
            for (int col = 0; col < hdr->tile cols;
                                                         enum BlockPartition bp = ...
                 col++)
                                                         if (bl != BL 8X8 && bp == PARTITION SPLIT) {
                                                             for (int n = 0; n < 4; n++)
                decode tile sbrow(...);
                                                                 decode sb(\ldots, bl + 1);
                                                         } else {
            postfilter sbrow(...);
                                                             for (int n = 0; n < n blks[bp]; n++)
                                                                 decode b(.., blk sz[bl][bp][n]);
```

High-level overview of decoding process (3)

decode_b(), pass != 2, symbol parsing

```
typedef struct Av1Block {
   uint8 t bl, bs, bp;
   uint8 t intra, seg id, skip mode, skip, uvtx;
   union {
        struct {
            uint8 t y mode, uv mode, tx, pal sz[2];
            int8 t y angle, uv angle, cfl alpha[2];
        }; // intra
        struct {
            int8 t ref[2];
            uint8 t comp type, wedge idx, mask sign;
           uint8 t inter mode, drl idx;
            uint8 t interintra type, interintra mode;
            uint8 t motion mode;
            uint8 t max ytx, filter2d;
            uint16 t tx split[2];
            mv mv[2];
        }; // inter
    };
 Av1Block;
```

+ palette, palette indices, transform type, transform coefficients

- Each tile (row/col) in pass 1 is completely independent and can run in its own thread
- In theory, we could signal completion of each individual tile_sbrow (as a bitmask) so that subsequent threads (for ref_mvs or seg_ids) could wait on that tile-independently
 - However, ATM, we only signal sbrow completion linearly
- After pass 1, entropy context signaling causes subsequent frame threads that depend on this entropy context to be woken up so their pass 1 can start

High-level overview of decoding process (4)

decode_b(), pass != 1, reconstruction



- Each tile_col is independent and can run in its own thread
 - For each inter block, we wait for the reference frame thread to have completed reconstruction of that sbrow
- After completion of each sbrow, we signal the main frame thread to process the next postfilter_sbrow
 - Postfilter is not yet threaded, but we may add that later if it has merit
- The main thread then signals progression of block reconstruction to any subsequent frame waiting for completion of this sbrow





Next steps for dav1d:

- Finish everything
- 12 bits/component
- Film grain
- SIMD
- More platforms
- Unit tests, fuzzing

Features

- 8+10 bits/component
- All bitstream tools
- Fast, small, efficient
- Multi-threaded (tile + frame)

We need you!



We need you to contribute!

- Code
 - SIMD
 - Platforms ports
 - Tools & Bindings
- Use it!
 - In your app
- Contribute/donate!

Questions?

Thanks to the Alliance for Open Media for sponsoring this work!